

# Expand Your KIM!

## Part 4: a TTY substitute

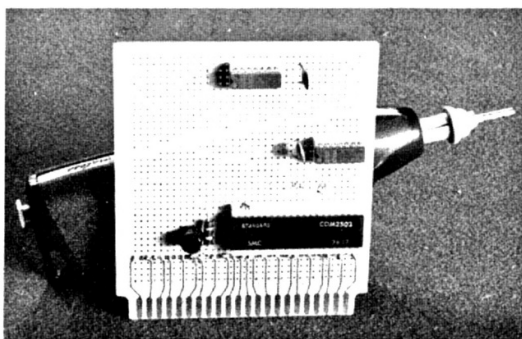


Photo 1. This \$10 circuit makes an SWTP keyboard and PR-40 printer act like a miniature Teletype.

Even if you are not building the KIM-1 System described in the first three parts of this series, you may find this article interesting and useful.

The first section is devoted to converting the SWTP keyboard and PR-40 printer into a low-cost (\$310) teletypewriter. The latter portion of the article describes a method for adding an external keyboard and display to KIM.

In the KIM-1 System, many useful subroutines, including I/O, are provided in ROM. These routines operate over the KIM 20 mA TTY interface lines. The cost of even a reconditioned TTY was prohibitive for me, and

besides, the PR-40 printer was better suited to my requirement of portability.

To take full advantage of the ROM I/O routines, and to avoid using KIM's two non-dedicated I/O ports, I set out to construct a 20 mA serial interface for the PR-40 and the SWTP keyboard.

### Overview

Since the interface would deal primarily with TTL signals on both ends, I eliminated the optical isolation often found on other interfaces. My baud-rate frequency would be far from critical, since KIM automatically adjusts its software timing to match the incoming

signal. These considerations made possible a simple interface consisting of only three chips and one transistor.

The advantages of the KIM self-adjusting I/O routines are obvious, but, as it turns out, disadvantages are also present. The KIM-1 System utilizes a Dazzler for its video display (see last month's article), which puts the processor into a hold approximately 20 percent of the time so it may gain access to the bus for DMA. This delay creates the probability that the characters transferred during Dazzler operation will have faulty timing.

In addition, during observation of the above symptoms I found that the cable positions and mainframe wiring placement held potential noise problems from the Dazzler that could affect serial transfers. There are many methods of correcting either problem, but most corrections are more applicable to mass production where the designer will know the location of every wire and the length of each cable.

Not having this control over systems built by Kilo-baud readers, I chose to shut off the Dazzler during all transfers of serial data, thus eliminating any possible

timing or noise problems that might be introduced by the DMA operations.

Stopping the Dazzler naturally causes the video display to blank during data transfers; but since I'm transferring data at just over 5200 baud, the display only blanks for 2.1 ms, which is not noticeable.

This high data rate does provide a potential problem with the printer during carriage returns. The printer has a 40-character buffer memory and can accept data faster than any microprocessor can send it. However, during the carriage return (about one second), the inputs to the buffer are locked out, and any data transferred at that time is lost.

Most systems (including KIM) correct this problem by sending several nonfunctioning characters, such as nulls, after each carriage return, just to take up time. Although this works well for the standard TTY rate of 110 baud, it would take nearly 500 nulls for a one-second delay at 5200 baud.

I corrected this situation by putting the processor into a hold (thus stopping transfers) whenever a carriage return was in effect. Although I lose one second of processor time during carriage returns, I can load the buffer memory in only 85 ms as opposed to four seconds required at 110 baud. Obviously, I have increased my throughput time by as much as 500 percent with this method. One function of the interface is to convert the parallel data from the keyboard to compatible serial data for KIM. Compatible, in this case, means

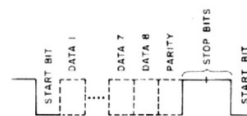


Fig. 1. Timing detail for serial transfers.

adding a start bit and two stop bits to each data word.

The serial data line normally remains at the high (logic 1) level, and a high-to-low transition (the start bit) is used to indicate the beginning of a new word of data. The high and low levels are often referred to, respectively, as marks and spaces.

Two stop bits (marks) follow the actual data. It should be noted that all words contain the same number of data bits, and the stop bits are *not* used to indicate the end of a word. The stop bits have two functions. First, if either of the stop bits happens to be a zero, a framing error (timing) is probably indicated. Second, if the data words are following each other without an elapsed time between them, the mark condition of the stop bits assures that the negative edge of the start bit will be properly recognized. If this is not clear, imagine two words without stop bits in which the last bit of word one was a space. Obviously, if a mark-to-space transition is to be recognized, the line must return to the mark condition before the second word. Fig. 1 shows the timing for the serial data.

The second function of the interface is exactly oppo-

site of the parallel-to-serial conversion just described. It is to convert the serial data (coming from KIM) to the parallel data required by the printer, and the generation of a strobe to initiate the actual parallel transfer.

Generally, the above functions could be implemented with shift registers under proper control. Fortunately, the shift registers and the control circuitry are available in a single chip called a universal asynchronous receiver transmitter (UART).

I chose a 2502 UART because of its low cost, but most any will do if you study its data sheets and utilize it properly. Table 1 lists the pin usages for the 2502. Just remember that the UART is simply doing serial-to-parallel and parallel-to-serial conversions.

Fig. 2 is a page from my notebook showing the schematic of the interface, component placement and pinout designations. The circuit is built on a 44-pin board (see Photo 1).

#### How It Works

The operation of the interface is simple: The 7492 is used as a divide-by-12 counter to lower the frequency applied to the UART.

The serial data coming

Pin	Function
1	5 volt supply.
2	-12 volt supply.
3	Ground.
4	Grounded to keep parallel outputs enabled.
5-12	Parallel outputs.
13	High-level output indicates parity error (not used).
14	High-level output indicates framing error (not used).
15	High-level output indicates parallel outputs are not taken before new character is received (not used).
16	Grounded to enable outputs of pins 13, 14, 15, 19 and 22.
17	Clock input (output baud rate is 1/16 of this frequency).
18	Low-level input resets pin 19 to a low level.
19	High-level output indicates the parallel outputs are valid.
20	Serial input.
21	High-level pulse causes Master Reset.
22	High level indicates parallel input buffer empty (not used).
23	Low-level pulse enters parallel data.
24	High-level output between serial transmissions (not used).
25	Serial output.
26-33	Parallel inputs.
34	High level enables pins 35, 36, 37, 38 and 39.
35	High level eliminates parity.
36	High level sets two stop bits.
37-38	High levels indicate eight-bit character.
39	Indicates even or odd parity (not used).
40	Clock input (must be 16 times baud rate).

Table 1. Pin functions for the 2502 UART.

from KIM is from an open collector NAND gate. When a logic 1 is being output to the printer, this gate has a low output, thus sinking the 20 mA signal provided by the printer return. I shorted the gate output and the return together (pins 6 and 8 on the interface card) causing the gate to act as standard TTL, except that the signal is inverted. I used gate A1 (see schematic) to invert this sig-

nal so the UART was receiving the correct information.

The UART converts the serial data from A1 to parallel and sends it to the printer under control of the high-level strobe (UART pin 19). Gate A2 converts this signal to the low-level strobe required by the printer.

The keyboard inputs its parallel data by pulsing the UART pin 23. The serial output is used to control the conduction of transistor Q1, which can be almost any NPN transistor. The transistor simply makes and breaks the 20 mA input loop on KIM.

Gate A3 inverts the low-level KIM reset to a high-level pulse for the UART.

Gate A4 is used as a buffer (pin 2 of the interface card is shorted to ground when the Dazzler power switch is off). Since pin 2 connects to the S-100 clear, *either* the Dazzler power switch or the depression of a key will cause the Dazzler to halt the DMA operations, thus preventing possible noise and timing problems as described earlier. Naturally, since the Dazzler is turned off when a key is pressed, it must be turned back on when the character

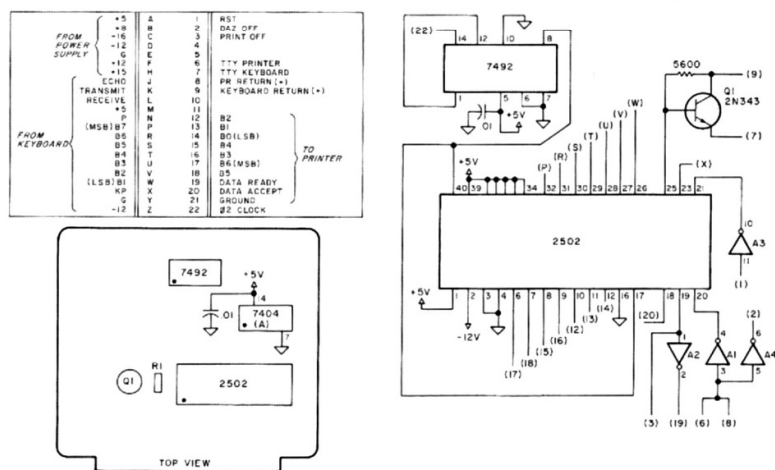


Fig. 2. Interface schematic.

has been transferred. The software example later in this article shows how this can be accomplished.

Note that when pin 3 of the interface card is shorted

to ground by the Print power switch, transfers to the printer will be inhibited because the UART strobe signal is eliminated.

If you are constructing the

KIM-1 System, do not pass lightly over these switch configurations since they provide useful functions that are not readily obvious.

Since the four TTY lines

from KIM also connect to banana plugs on the backplane, an auxiliary TTY or video display may be easily connected to the system. The only requirement is that the

Address	Instruction	Label	Mnemonic	Comment
0300	D8	INIT	CLD	Select binary mode.
01	A9 00		LDA #00	
03	85 00		STA Color	Clear color.
05	A9 10		LDA #010	Sets Dazzler to a
07	8D 0F 80		STA DAZ1	32 x 32 color mode.
0A	A9 90		LDA #090	Sets starting address
0C	8D 0E 80		STA DAZ2	for display to page 20.
; Stores color in all of display area.				
0F	A2 FF	ALL	LDX #0FF	Initialize Index X.
11	A5 00	ALL1	LDA Color	Get color.
13	9D 00 20		STA(2000),x	Store according to x.
16	8A		TXA	Get index.
17	F0 04		BEQ INTEN	Branch if finished.
19	CA		DEX	Decrement x if not.
1A	4C 11 03		JMP ALL1	Do it again.
1D	20 7C 03	INTEN	JSR INPUT	Input from keyboard.
20	CA 48		CMP "H"	Is character an "H"
22	F0 05		BEQ HIGH	Branch if yes.
24	A9 00		LDA 00	Prepare for low intensity.
26	4C 2B 03		JMP LOW	Go around high.
29	A9 08	HIGH	LDA #008	Set high intensity bit.
2B	85 00	LOW	STA Color	Save intensity.
2D	20 7C 03	SHADE	JSR INPUT	Get shade.
30	29 07		AND #007	Change ASCII to binary.
32	05 00		OR Color	Combine shade and intensity.
34	85 00		STA Color	Save color (right byte)
36	0A	ASL		
37	0A	ASL		Form color in
38	0A	ASL		left byte.
39	0A	ASL		
3A	05 00		ORA Color	Combine left and right.
3C	85 00		STA Color	True full color.
3E	9D 00 20	STORE	STA(2000),x	Puts color on display.
; Decodes next command.				
41	20 7C 03	DECODE	JSR INPUT	Get command.
44	C9 4E		CMP "N"	Is it an "N"
46	D0 03		BNE NEXTA	Branch if not
48	4C 1C 03		JMP INTEN	Prepare for new color.
4B	C9 41	NEXTA	CMP "A"	Is it an "A?"
4D	D0 03		BNE NEXTU	Branch if not.
4F	4C 0F 03		JMP ALL	Jump if yes.
52	C9 55	NEXTU	CMP U	Is it a "U?"
54	D0 08		BNE NEXTD	Branch if not.
56	8A		TXA	Prepare to change pointer.
; Move pointer vertically				
57	38		SEC	Prepare to subtract.
58	E9 10		SBC #16	Subtract
5A	AA		TAX	Restore pointer.
5B	4C 77 03		JMP CONTIN	Continue
5E	C9 44	NEXTD	CMP "D"	Is it a "D?"
60	D0 08		BNE NEXTL	Branch if not.
62	8A		TXA	Prepare to change pointer.
63	18		CLC	Prepare to add.
64	69 10		ADC #16	ADD
66	AA		TAX	Restore pointer.
67	4C 77 03		JMP CONTIN	Continue
6A	C9 4C	NEXTL	CMP "L"	Is it an "L?"
6C	D0 04		BNE NEXTR	Branch if not.
6E	CA		DEX	Modify pointer.
6F	4C 77 03		JMP CONTIN	Continue
72	C9 52	NEXTR	CMP "R"	Is it an "R?"
74	D0 01		BNE CONTIN	Branch if not.
76	E8		INX	Modify pointer.
77	A5 00	CONTIN	LDA Color	Get color.
79	4C 3E 03		JMP STORE	Start over.
; Subroutine to get character and turn Dazzler back on				
7C	20 5A 1E	INPUT	JSR GETCHAR	
7F	85 01		STA TEMP	Save accumulator.
81	A9 90		LDA #090	
83	8D 0E 80		STA DAZZ	Turns Dazzler on.
86	A5 01		LDA TEMP	Restores accumulator.
88	60		RTS	

Program listing.

Typing A colors *all* the

When I first looked

A little study will show, however, that a keyboard connected in that way will lack the three functions described above.

I decided to add three sockets to KIM and interface my external keyboard and display through them. The sockets were mounted by drilling holes with a #60 (no larger) drill bit for the pins. The wire was crimped around the solder tails of each pin. This connection, when





The display could be handled in the same way, but I chose to cut the foil lines on KIM that provided the multiplexed power lines to the LEDs so that only the ex-

Most of your front panel is now operational; the next article on the external interface board will complete the system's hardware, bringing to life the sense switches, joysticks and D/A ports. ■

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