

# A Printer for the KIM or SYM

*The ubiquitous Selectric finds yet another home.*

After I expanded my KIM-1 with a CRT terminal, 28K of additional RAM and Micro-Z's Microsoft BASIC ("Another KIM-1 Expansion," September 1979, p. 130), I felt the need to add hard-copy printout to the system. This article describes how I accomplished this goal and interfaced to my new SYM-1 as well.

## The Selectric

Various models of IBM Selectric I/O typewriters are currently being removed from service and made available to the hobbyist for very reasonable prices. I was able to obtain a surplus Model 2970 Communications Terminal a short time ago for only \$100! The reasonable price and high-quality printing available made it the printer of my choice. There was only one minor problem: I'd have to design the interface between the printer and the KIM.

The 2970 consisted of a power supply, logic assembly, cabinet and a Model 735 Selectric I/O typewriter. The Selectric contained all of the selector magnets (solenoids, for those who don't speak IBMese!) for tilt, rotate, index, carriage return and non-print (space).

I stripped the electronics out of the cabinet but left the power supply. AC power to the supply and the Selectric is controlled by a circuit breaker on the cabinet, which is a convenient base for the Selectric to sit on. The remaining interface requirement was to ground the proper leads from the selector magnets with the correct coding and timing. The KIM, using its on-board

timer and I/O capability, should easily handle these functions.

## Interfacing Options

There are two ways to interface to a Selectric I/O—open loop or closed loop. With a closed loop system, signals generated by the Selectric mechanism are used to control the character timing. This is the preferred interface if heavy use is planned, but is somewhat more difficult to accomplish.

An open loop interface always must provide the worst-case timing. A character is sent out, and then the interface waits for the longest time it will take to print any character before sending another. The IBM manuals state that either method can be implemented successfully. However, open loop timing will slow down the throughput by a small amount.

The main disadvantage of the open loop system, in my opinion, is that the cycle clutch must stop the machine after each character. In a closed loop system, the next character can be transmitted prior to the clutch action, thus saving machine wear and tear. A closed loop system requires that the feedback contacts be carefully adjusted and that additional control lines be connected from the Selectric to the interface electronics.

The unexpanded KIM-1 only has 15 I/O lines available, and some of these on my KIM were already in use. I came up with the circuit shown in Fig. 1 to interface the KIM to the Selectric using only eight lines or one

port address.

This is an open loop type of interface, but since I'm not planning on printing reams of paper daily, I don't expect the open loop disadvantages to be as important as the requirement for minimum I/O lines, minimum hardware and overall simplicity. It has been working satisfactorily now for several months. My biggest problem in getting it running was a misadjusted escape-

ment mechanism inside the machine.

## Implementing the Interface

I highly recommend that anyone attempting to interface or use a Selectric I/O typewriter obtain copies of IBM manuals 225-6595-1 and 225-1726-6. Along with the spare parts manual 123-1008-3, they contain a wealth of information on the machine's operation. Almost any

Listing 1. KIM interface program.

```

1 ; KIM SELECTRIC DRIVER
2 ;
3 ; Routine to convert ASCII in accumulator
4 ; to Selectric codes, and send to Selectric with
5 ; proper timing, case, etc. if location 0400 hex
6 ; is not equal to zero. Returns to KIM routine OUTCHR
7 ; with all registers unchanged from entry. Uses no
8 ; page zero locations.
9
10 PAD: equ $1700 ; Output port to Selectric
11 PAD0: equ $1701 ; Selectric output register
12 TIMER: equ $1702 ; Divide by 1024 register
13 OUTCHR: equ $1E40 ; routine to send ASCII to CRT
14 TypeOn: equ $0400 ; Zero = Don't type
15 ASCII: equ $0401 ; Temporary
16 CRflag: equ $0402 ; Storage
17 Temp: equ $0403 ; Buffer
18 SFFflag: equ $0405 ; locations
19 org $0406 ;
20 Start: ; Start of program
21 PHP ; Save registers
22 LDA TypeOn ; Check if typing desired
23 BNE Type ; Yes then typing
24 PLA ; No restore registers
25 PLP ;
26 JMP OUTCHR ; and send to CRT
27 Type: LDA #FF ; Set port to output
28 STA PAD0 ;

```

```

0417:68 01 29 PLA ; Get ASCII code
0418:86 01 30 STA ASCII ; Save it
0419:46 01 31 PHA ; Save registers
041C:8A 32 TAX ;
041D:46 33 PHA ;
041E:98 34 TRA ;
041F:46 35 PHA ;
0420:D8 36 CLD ; Binary mode
0421:40 01 04 37 LDA ASCII ; Get ASCII code
0424:C9 20 38 CMP #20 ; Is it a space?
0426:F0 17 39 BEQ Xspace ; Yes
0428:10 31 40 BPL GetCode ; Greater than space = valid code
042A:C9 08 41 CMP #8 ; Less than space: is it Return?
042C:D0 15 42 BNE CRLF ; no, go check if is a line feed
042E:A4 04 43 LDA #304 ; yes, carriage return
0430:81 02 04 44 STA CRLF ; set flag to non-zero
0433:A8 45 TAY ; Will send four characters
0434:A4 00 46 LDA #500 ; but next three characters will
0436:81 03 04 47 STA Temp ; be nulls to allow for return
0439:A4 40 48 LDA #540 ; Carriage return code
043B:A2 7F 49 LDX #57F ; long delay
043D:D3 57 50 BNE CharOut ; send the carriage return
043F:A9 81 51 Xspace: LDA #581 ; Space code
0441:D0 45 52 BNE Out1 ; Send it
0443:C9 0A 53 CKLF: CMP #50A ; Is code a line feed?
0445:D0 72 54 BNE Return ; No, ignore it
0447:A0 02 04 55 LDA CRLF ; Check flag
044A:F0 07 56 BEQ Linefeed ; Send LF if last not Return
044C:A9 00 57 LDA #500 ; Last character sent was Return
044E:D0 02 04 58 STA CRLF ; reset the flag
0451:F0 66 59 BEQ Return ; and ignore the line feed
0453:A0 01 60 Linefeed: LDX #501 ; one character
0455:A2 7F 61 LDX #57F ; long delay
0457:A9 20 62 LDA #520 ; line feed code
0459:D0 38 63 BNE CharOut ; send the line feed
045B:28 7F 64 AND #7F ; mask off high bit
045D:A4 65 TAX ;
045E:D8 A1 04 66 LDA Codes->21 ; Get code in accumulator
0460:D8 67 LDA #10A ; shift left, put case in carry
0462:90 11 68 BCC LChar ; Lower Case?
0464:AC 05 04 69 LDX SFFlag ; no, check case flag
0466:D0 1F 70 BNE Out1 ; Already in Upper Case, then send
0468:D8 03 04 71 STA Temp ; Need Case changer, save code
046A:D0 02 72 LDX #502 ; will send two characters
046C:D0 05 04 73 STX SFFlag ; Set shift flag, Non zero = Upper
046E:A9 10 74 LDA #510 ; Shift code
0470:D0 15 75 BNE Out2 ; Toggle shift, then send character
0472:AC 05 04 76 LDX SFFlag ; Lower case character, check case
0474:D0 0E 77 BEQ Out1 ; Already in lower case, then send
0476:D8 03 04 78 STA Temp ; Need Case changer, save code
0478:A9 00 79 LDA #500 ; Reset shift flag
047A:D8 05 04 80 STA SFFlag ; Zero = Lower Case
047C:A9 10 74 LDA #510 ; Shift code
047E:D0 15 75 BNE Out2 ; Toggle shift, then send character
0480:A9 01 84 Out1: LDX #501 ; will send two characters
0482:A2 02 81 LDX #510 ; Shift code
0484:A9 10 82 LDA #500 ; Toggle case, then send character
0486:A0 02 83 LDX #501 ; will send one character
0488:A0 01 84 Out2: LDX #500 ; don't forget to reset
048A:A2 00 85 Out2: STX CRLF ; the carriage return flag
048C:D8 02 04 86 LDX #540 ; normal delay time
048E:A2 04 87 BNE CharOut ; Send the character
0490:A0 03 04 88 LDA Temp ; get additional character(s)
0492:D0 17 90 CharOut: STA PAD ; Put in output port
0494:A9 0A 91 LDA #50A ; OA = 10 milliseconds
0496:D8 07 17 92 STA Timer ; set timer
0498:A9 07 17 93 STA Timer ; make sure
049A:D8 07 17 94 Delay1: LDA Timer ; check timer
049C:A0 F8 95 BPL Delay1 ; still counting, check again
049E:A9 00 96 LDA #500 ; Timer timed out
04A0:D8 00 17 97 STA PAD ; turn off port
04A2:D8 07 17 98 STX Timer ; start delay time
04A4:D8 07 17 99 STX Timer ; make sure

```

```

04B1:AD 07 17 100 Delay2: LDA Timer ; check timer
04B4:10 F8 101 BPL Delay2 ; still counting, check again
04B6:D8 102 BEY ; Delay over, More Characters?
04B8:D0 DA 103 BNE Char2 ; Yes, then send them
04BA:68 104 Return: PLA ; No, restore all registers
04BC:A8 105 TAY ;
04BE:A8 106 PLA ;
04C0:AA 107 TAX ;
04C2:D8 108 PLA ;
04C4:E2 109 PLP ;
04C6:4C AD 1E 110 JMP OUTCHR ; and send character to CRT
04C8:11 111 ;
04CA:11 112 ; Control Code Table for IBM Ball 952
04CC:11 113 ; Bit 1=Function
04CE:11 114 ; 0 Tilt 1
04D0:11 115 ; 1 Tilt 2
04D2:11 116 ; 2 Rotate 1
04D4:11 117 ; 3 Rotate 2
04D6:11 118 ; 4 Rotate 2A
04D8:11 119 ; 5 Rotate -5
04DA:11 120 ; 6 Check
Return 2 1209 0489
SFFlag 2 1029 0405
Start 2 1030 0406
Temp 2 1027 0403
Timer 2 5895 1707
Type 2 1042 0412
TypeOn 2 1024 0400
Xspace 2 1087 043F
121 ; 7 Upper Case
122 ;
123 ;
04C2:C1 124 Codes: byte AC1 ; 21 1
04C3:C7 125 byte SC7 ; 22 "
04C4:43 126 byte AC3 ; 23 #
04C5:A1 127 byte AC1 ; 24 $
04C6:D0 128 byte AC7 ; 25 %
04C7:50 129 byte AC7 ; 26 &
04C8:E7 130 byte AC7 ; 27 *
04C9:FF 131 byte FF ; 28 (
04CA:EF 132 byte EF ; 29 )
04CB:EB 133 byte EB ; 2A +
04CC:D8 134 byte D8 ; 2B -
04CD:42 135 byte AC2 ; 2C =
04CE:5E 136 byte AC2 ; 2D ~
04CF:40 137 byte AC0 ; 2E ^
04D0:7E 138 byte AC7 ; 2F /
04D1:5F 139 byte AC7 ; 30 0
04D2:7F 140 byte AC7 ; 31 1
04D3:5B 141 byte AC3 ; 32 2
04D4:7B 142 byte AC7 ; 33 3
04D5:4F 143 byte AC7 ; 34 4
04D6:0F 144 byte AC7 ; 35 5
04D7:4B 145 byte AC7 ; 36 6
04D8:6B 146 byte AC7 ; 37 7
04D9:07 147 byte AC7 ; 38 8
04DA:A7 148 byte AC7 ; 39 9
04DB:C2 149 byte AC2 ; 3A :
04DC:C0 150 byte AC0 ; 3B ;
04DD:F0 151 byte AC7 ; 3C <
04DE:C3 152 byte AC3 ; 3D =
04DF:D0 153 byte AC0 ; 3E >
04E0:D0 154 byte AC0 ; 3F ?
04E1:5C 155 byte AC2 ; 40 "at"
04E2:FC 156 byte AC7 ; 41 A
04E3:D8 157 byte AC7 ; 42 B
04E4:F8 158 byte AC7 ; 43 C

```

04E5:CC	159	byte \$CC :	44	D	050E:4D	200	byte \$4D :	6D	m
04E6:EC	160	byte \$EC :	45	E	050F:6D	201	byte \$6D :	6E	n
04E7:C8	161	byte \$C8 :	46	F	0510:49	202	byte \$49 :	6F	o
04E8:E8	162	byte \$E8 :	47	G	0511:69	203	byte \$69 :	70	p
04E9:E4	163	byte \$E4 :	48	H	0512:65	204	byte \$65 :	71	q
04EA:C4	164	byte \$C4 :	49	I	0513:45	205	byte \$45 :	72	r
04EB:FD	165	byte \$FD :	4A	J	0514:5A	206	byte \$5A :	73	s
04EC:D9	166	byte \$D9 :	4B	K	0515:7A	207	byte \$7A :	74	t
04ED:F9	167	byte \$F9 :	4C	L	0516:4E	208	byte \$4E :	75	u
04EE:CD	168	byte \$CD :	4D	M	0517:6E	209	byte \$6E :	76	v
04EF:ED	169	byte \$ED :	4E	N	0518:4A	210	byte \$4A :	77	w
04F0:C9	170	byte \$C9 :	4F	O	0519:6A	211	byte \$6A :	78	x
04F1:E9	171	byte \$E9 :	50	P	051A:66	212	byte \$66 :	79	y
04F2:E5	172	byte \$E5 :	51	Q	051B:46	213	byte \$46 :	7A	z
04F3:C5	173	byte \$C5 :	52	R	051C:FF	214	byte \$FF :	7B	{
04F4:DA	174	byte \$DA :	53	S	051D:C0	215	byte \$C0 :	7C	cent sign
04F5:FA	175	byte \$FA :	54	T	051E:EF	216	byte \$EF :	7D	}
04F6:CE	176	byte \$CE :	55	U	051F:80	217	byte \$80 :	7E	del
04F7:EE	177	byte \$EE :	56	V	0520:80	218	byte \$80 :	7F	del
04F8:CA	178	byte \$CA :	57	W					
04F9:EA	179	byte \$EA :	58	X					
04FA:E6	180	byte \$E6 :	59	Y					
04FB:C6	181	byte \$C6 :	5A	Z					
04FC:FF	182	byte \$FF :	5B	{					
04FD:DF	183	byte \$DF :	5C	}					
04FE:EF	184	byte \$EF :	5D	~					
04FF:CF	185	byte \$CF :	5E	^					
0500:FE	186	byte \$FE :	5F	~					
0501:E7	187	byte \$E7 :	60	a					
0502:7C	188	byte \$7C :	61	b					
0503:58	189	byte \$58 :	62	c					
0504:78	190	byte \$78 :	63	d					
0505:4C	191	byte \$4C :	64	e					
0506:6C	192	byte \$6C :	65	f					
0507:48	193	byte \$48 :	66	g					
0508:68	194	byte \$68 :	67	h					
0509:64	195	byte \$64 :	68	i					
050A:44	196	byte \$44 :	69	j					
050B:7D	197	byte \$7D :	6A	k					
050C:59	198	byte \$59 :	6B	l					
050D:79	199	byte \$79 :	6C						

#### reference name table

name	size	dec	hex
ASCII	2	1025	0401
CKLF	2	1091	0443
CRflag	2	1026	0402
Char2	2	1171	0493
CharOut	2	1174	0496
Codes	2	1218	04C2
Delay1	2	1185	04A1
Delay2	2	1201	04B1
GetCode	2	1115	045B
LCchar	2	1141	0475
Linefeed	2	1107	0453
OUTCHR	2	7840	1EA0
Out1	2	1160	0488
Out2	2	1162	048A
PAD	2	5888	1700
PADD	2	5889	1701

Listing 2 . SYM interface program.

```

1 : SYM SELECTRIC DRIVER
2 :
3 : Routine to convert ASCII in accumulator
4 : to Selectric codes, and send to Selectric with
5 : proper timing, case, etc. if location 1FFF hex
6 : is not equal to zero. Returns to SYM routine TOUT
7 : with all registers unchanged from entry. Uses no
8 : page zero locations.
9 : Change OUTVEC to TEE0 to use. ( SD TEE0, A664 )
10 : In response to "Memory Size" from BASIC, enter 7903
11 : This routine uses the top 288 bytes of an 8K SYM memory.
12 :
13 PAD: equ $A830 ; Output port to Selectric
14 PADD: equ $A832 ; Data direction register
15 Timer: equ $A417 ; Divide by 1024
16 TOUT: equ $8A4D ; SYM routine, sends ASCII to CRT
17 TypeOn: equ $1FFF ; Zero = Don't type
18 ASCII: equ $1FFE ; Temporary
19 CRflag: equ $1FFD ; Storage
20 Temp: equ $1FFC ; buffer
21 SFTflag: equ $1FFB ; locations
22
23 Start: PHP ; Start of program
24 PHA ; Save flags & accumulator
25 LDA TypeOn ; Check if Typing desired
26 BNE Type ; Yes, then Type
27 PLA ; No, restore accumulator
28 PLP ; and flags
29 JMP TOUT ; and send to CRT
30 Type: LDA #FFF ; Set port to output
31 STA PADD ;
32 PLA ; Get ASCII code
33 STA ASCII ; Save it
34 PHA ; Save registers
35 TXA ;
36 PHA ;
37 TXA ;
38 PHA ;
39 CLD ; Binary mode
40 LDA ASCII ; Get ASCII code
41 CMP #20 ; Is it a space?
42 BEQ Xspace ; Yes, then send a space
43 BPL GetCode ; > space is valid code
44 CMP #0D ; < space, is it Return?
45 BNE CKLF ; no, go check if it is a line feed
46 LDA #0D ; yes, carriage return
47 STA CRflag ; Set flag to non-zero
48 TAY ; Will send four characters
49 LDA #0D ; but next three characters will

```

Selectric I/O could be interfaced using the information in this article and in those manuals.

The 2970 Selectric was originally used in a motel/hotel reservation system, according to its type ball, which had funny little symbols that would only be useful in printing a hotel bill, uppercase letters only, the numbers and only a few standard punctuation marks. I obtained a number 952 ball to replace it.

The 952 ball has both upper and lowercase letters, numbers and most of the ASCII symbols. I did not convert the interposers of the machine to match the new ball, so it was useless as a typewriter. But I'm only using it as a printer, so why waste the time and money on the interposers?

Another peculiarity (?) of the 2970 Selectric is that a space is considered a printable character and is obtained by energizing the non-print magnet along with one or more of the tilt, rotate or check magnets. I understand that a space is a control character on some of the other Selectric I/O machines. They would require slight modification of the hardware and software interfaces contained in

```

1F10:8D FC 1F 50 STA Temp ; be nulls to allow for return
1F13:A9 40 51 LDA #340 ; Carriage return code
1F15:A2 7F 52 LDX #37F ; Long delay
1F17:0D 57 53 BNE CharOut ; Send the carriage return
1F19:A9 81 54 Xspace: LDA #81 ; Space code
1F1B:0D 45 55 BNE Out1 ; Send it
1F1D:C9 0A 56 CKLF: CMP #30A ; Is code a line feed?
1F1F:0D 72 57 BNE Return ; No, ignore it
1F21:AD FD 1F 58 LDA CRflag ; Check flag
1F24:FD 07 59 BEQ Linefeed ; Send LF if last not Return
1F26:A9 00 60 LDA #30D ; Last character sent was Return
1F28:8D FD 1F 61 STA CRflag ; reset the flag
1F2B:FD 66 62 BEQ Return ; and ignore the line feed
1F2D:A0 01 63 Linefeed: LDY #301 ; one character
1F2F:A2 7F 64 LDX #37F ; Long delay
1F31:A9 20 65 LDA #320 ; line feed code
1F33:0D 3B 66 BNE CharOut ; send the line feed
1F35:29 7F 67 GetCode: AND #37F ; mask off high bit
1F37:AA 68 TAX ; put in index X
1F38:BD 7B 1F 69 LDA Codes-$21,X ; Get code in Accumulator
1F3B:0A 70 ASLA ; shift left, put case in carry
1F3C:90 11 71 ECC LCchar ; Lower Case?
1F3E:AC FB 1F 72 LDY SFFflag ; no, check case flag
1F41:0D 1F 73 BNE Out1 ; In Upper Case, send character
1F43:8D FC 1F 74 STA Temp ; Need Case change, save code
1F46:A0 02 75 LDY #302 ; will send two characters
1F48:8C FB 1F 76 STY SFFflag ; Set shift flag, Non zero = Uppercase
1F4B:A9 10 77 LDA #310 ; Shift code
1F4D:0D 15 78 BNE Out2 ; Toggle shift, then send character
1F4F:AC FB 1F 79 LCchar: LDY SFFflag ; Lower case character, check case
1F52:FD 0E 80 REQ Out1 ; In lower case, send character
1F54:8D FC 1F 81 STA Temp ; Need Case change, save code
1F57:A9 00 82 LDA #30D ; Reset shift flag
1F59:8D FB 1F 83 STA SFFflag ; Zero = Lower Case
1F5C:A0 02 84 LDY #302 ; will send two characters
1F5E:A9 10 85 LDA #310 ; Shift code
1F60:0D 02 86 BNE Out2 ; Toggle case, then send character
1F62:A0 01 87 Out1: LDY #301 ; will send one character
1F64:A2 00 88 Out2: LDX #30D ; don't forget to reset
1F66:8E FD 1F 89 STX CRflag ; the carriage return flag
1F69:A2 40 90 LDX #340 ; normal delay time
1F6B:0D 03 91 BNE CharOut ; Send the character
1F6D:A0 FC 1F 92 Char2: LDA Temp ; get additional character
1F70:8D 00 A3 93 CharOut: STA PAD ; Put in output port
1F73:A9 0A 94 LDA #30A ; 3A = 10 milliseconds
1F75:8D 17 A4 95 STA Timer ; set timer
1F78:8D 17 A4 96 STA Timer ; make sure
1F7B:AD 17 A4 97 Delay1: LDA Timer ; check timer
1F7E:10 FB 98 BPL Delay1 ; still counting, check again
1F80:A9 00 99 LDA #30D ; Timer timed out
1F82:8D 00 A8 100 STA PAD ; turn off port
1F85:8E 17 A4 101 STX Timer ; start delay time
1F88:8E 17 A4 102 STX Timer ; make sure
1F8B:AD 17 A4 103 Delay2: LDA Timer ; check timer
1F8E:10 FB 104 BPL Delay2 ; still counting, check again
1F90:88 105 DEY ; Delay over, Any more Characters?
1F91:0D DA 106 BNE Char2 ; Yes, then send them
1F93:68 107 Return: PLA ; No, restore all registers
1F94:A8 108 TAX ;
1F95:68 109 PLA ;
1F96:AA 110 TAX ;
1F97:68 111 PLA ;
1F98:28 112 PLP ;
1F99:4C A0 BA 113 JMP TOUT ; and send character to CRT
114 ;
115 ; Control Code Table for IBM Ball 952
116 ; Bit 1=Function
117 ; 0 Tilt 1
118 ; 1 Tilt 2
119 ; 2 Rotate 1
120 ; 3 Rotate 2
121 ; 4 Rotate 2A
122 ; 5 Rotate -5
123 ; 6 Check
124 ; 7 Upper Case
125 ;
126 ; ASCII Printed
127 Codes: byte $C1 ; 21 !
128 byte $C7 ; 22 "
129 byte $A3 ; 23 #
130 byte $A1 ; 24 $
131 byte $DC ; 25 %
132 byte $5D ; 26 &
133 byte $E7 ; 27 '
134 byte $FF ; 28 (
135 byte $EF ; 29 )
136 byte $EB ; 2A *
137 byte $DB ; 2B +
138 byte $A2 ; 2C ,
139 byte $5E ; 2D -
140 byte $4D ; 2E .
141 byte $7E ; 2F /
142 byte $5F ; 30 0
143 byte $7F ; 31 1
144 byte $59 ; 32 2
145 byte $7B ; 33 3
146 byte $4F ; 34 4
147 byte $6F ; 35 5
148 byte $4B ; 36 6
149 byte $6B ; 37 7

```

this article, but the changes should not be difficult to accomplish.

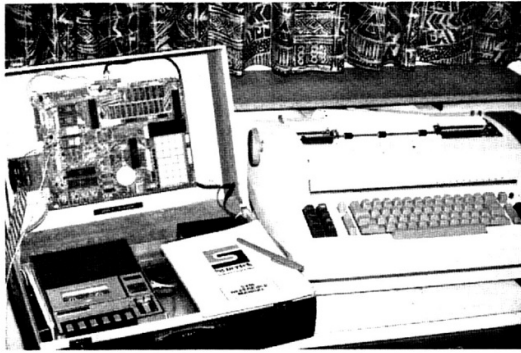
The control characters consist of Shift, Carriage Return and Index. Each time the Shift line is brought low, the machine changes case. It will stay in that case until the Shift line is pulsed again. This means that the KIM must keep track of what case the machine is in, only changing case when necessary. The SHIFT SYNC switch, a push-button type mounted on the Selectric, is used to initially synchronize it and the KIM as to which case is selected.

The Carriage Return function on the Selectric both returns the carriage to the left margin and advances the paper to the next print line. Therefore, the KIM must suppress any line-feed characters sent immediately after a Carriage Return, or double-spaced printing will result. Index is just IBMese for line feed and requires no further explanation.

The Check line is used in this interface scheme to differentiate between the printable and control characters. If CK in Fig. 1 is low, then CK will be high. Therefore, line D6, for example, activates U5B (ROT 5) and not U5C (Return). If CK were high, the reverse would be true. This multiplexing of the data lines allows the eight-bit port to control the eleven different signals needed by the Selectric.

Fig. 1 is the schematic of the complete hardware interface I am using. U1 and U2 are mounted on a small board in the KIM cabinet. A six-foot twisted-pair cable connects from this board to another small board in the 2970 cabinet. The numbers on the lines inside the dotted oval correspond to the pin numbers of the DB-25 connectors I used to terminate the cable.

The second board contains U3, U4, U5 and eleven identical relay driver circuits as shown. The collectors of the MJE-340s are wired to the selector magnets using the original 2970 cables. The other sides of the selector magnets are connected by the original wiring to the +48 volt output from the power supply in the 2970 cabinet.



The Selectric and the SYM-1.

### Software

Most of the work of the interfacing has been left up to the KIM's software. It must provide for code conversion from ASCII to the codes that correspond to the appropriate tilt, rotate and check magnet combination for the type ball or select the required control character. It must keep track of the machine's case—upper or lower—suppress line feeds immediately preceded by carriage returns, etc. Also, it must provide the pulses with the proper timing.

All pulses should have a 10 millisecond duration with at least 67.5 milliseconds wait from the start of one pulse to the occurrence of another, except for Index and Carriage Return, which require even longer delays. Listing 1 accomplishes all of these functions in the KIM.

This program listing should be reasonably easy to follow. If not, I wasted a lot of time on comments. It is located in my block of memory starting at 0400 hex. To prevent possible interference with other programs, it uses no page zero locations. If you relocate the program, the scratch locations at \$0400-\$0405 and the references to them must be changed. The rest of the code should be completely relocatable without change.

To output a character, most application software packages use a JSR OUTCHR (20 A0 1E). This is located at \$2A51 in my version of BASIC, for example. Change it to JSR Start (20 06 04) to use the Selectric driver pro-

gram. The program ends with a JMP to OUTCHR, which will then print the character on the terminal and return to the application program.

If location 0400 hex is a zero, the character will not be printed on the Selectric. Changing \$0400 to any other value will cause the character to be printed. This can be done from BASIC using POKE 1024,9 to start printing and POKE 1024,0 to stop it.

### The SYM-1

Shortly after I got the Selectric working with the KIM, I obtained one of Synertek's new SYM-1 boards. Although it uses essentially the same expansion bus as the KIM and has many other similarities, none of my KIM programs that use the on-board keypad and display would run on the SYM without major changes due to the way the SYM addresses its peripherals. Tom Pittman's Tiny BASIC, however, was easier to interface to the SYM than to the KIM! The SYM's expanded monitor (version 1.1), BASIC on ROM, higher-speed cassette interface and up to 4K of RAM on-board are excellent features.

Listing 2 is the revised Selectric driver software for the SYM. The small board plugged onto the SYM's auxiliary applications connector to the left side of it in the accompanying photo contains U1 and U2 of the hardware interface. The cable connected to it runs to the Selectric. It connects to the SYM +5 V, ground and port B of 6522 U28.

1FB3:67	150	byte \$67 ;	38	R
1FB4:47	151	byte \$47 ;	39	9
1FB5:C2	152	byte \$C2 ;	3A	:
1FB6:CB	153	byte \$CB ;	3B	:
1FB7:FB	154	byte \$FB ;	3C	<
1FB8:C3	155	byte \$C3 ;	3D	=
1FB9:0D	156	byte \$0D ;	3E	>
1FBA:0E	157	byte \$0E ;	3F	?
1FBB:5C	158	byte \$5C ;	40	"at"
1FBC:FC	159	byte \$FC ;	41	A
1FBD:08	160	byte \$08 ;	42	B
1FBE:F8	161	byte \$F8 ;	43	C
1FBF:CC	162	byte \$CC ;	44	D
1FC0:EC	163	byte \$EC ;	45	E
1FC1:C8	164	byte \$C8 ;	46	F
1FC2:E8	165	byte \$E8 ;	47	G
1FC3:E4	166	byte \$E4 ;	48	H
1FC4:C4	167	byte \$C4 ;	49	I
1FC5:FD	168	byte \$FD ;	4A	J
1FC6:D9	169	byte \$D9 ;	4B	K
1FC7:F9	170	byte \$F9 ;	4C	L
1FC8:C0	171	byte \$C0 ;	4D	M
1FC9:E0	172	byte \$E0 ;	4E	N
1FCA:C9	173	byte \$C9 ;	4F	O
1FCB:E9	174	byte \$E9 ;	50	P
1FCC:E5	175	byte \$E5 ;	51	q
1FCD:C5	176	byte \$C5 ;	52	R
1FCE:0A	177	byte \$0A ;	53	S
1FCF:FA	178	byte \$FA ;	54	T
1FD0:CE	179	byte \$CE ;	55	U
1FD1:EE	180	byte \$EE ;	56	V
1FD2:CA	181	byte \$CA ;	57	W
1FD3:EA	182	byte \$EA ;	58	X
1FD4:E6	183	byte \$E6 ;	59	Y
1FD5:C6	184	byte \$C6 ;	5A	Z
1FD6:FF	185	byte \$FF ;	5B	[
1FD7:0F	186	byte \$0F ;	5C	]
1FD8:EF	187	byte \$EF ;	5D	^
1FD9:C7	188	byte \$C7 ;	5E	_
1FDA:FE	189	byte \$FE ;	5F	`
1FDB:E7	190	byte \$E7 ;	60	{
1FDC:7C	191	byte \$7C ;	61	a
1FDD:58	192	byte \$58 ;	62	b
1FDE:78	193	byte \$78 ;	63	c
1FDF:4C	194	byte \$4C ;	64	d
1FE0:6C	195	byte \$6C ;	65	e
1FE1:48	196	byte \$48 ;	66	f
1FE2:68	197	byte \$68 ;	67	g
1FE3:64	198	byte \$64 ;	68	h
1FE4:44	199	byte \$44 ;	69	i
1FE5:70	200	byte \$70 ;	6A	j
1FE6:59	201	byte \$59 ;	6B	k
1FE7:79	202	byte \$79 ;	6C	l
1FE8:40	203	byte \$40 ;	6D	m
1FE9:60	204	byte \$60 ;	6E	n
1FEA:49	205	byte \$49 ;	6F	o
1FEB:69	206	byte \$69 ;	70	p
1FEC:65	207	byte \$65 ;	71	q
1FED:45	208	byte \$45 ;	72	r
1FEE:5A	209	byte \$5A ;	73	s
1FEF:7A	210	byte \$7A ;	74	t
1FF0:4E	211	byte \$4E ;	75	u
1FF1:6E	212	byte \$6E ;	76	v
1FF2:4A	213	byte \$4A ;	77	w
1FF3:6A	214	byte \$6A ;	78	x
1FF4:66	215	byte \$66 ;	79	y

### reference name table

name	size	dec	hex
ASCII	2	8190	1FFE
CKLF	2	7965	1F1D
CRflag	2	8189	1FFD
Char2	2	8045	1F6D
CharOut	2	8048	1F70
Codes	2	8092	1F9C
Delay1	2	8059	1F7B
Delay2	2	8075	1F8B
GetCode	2	7989	1F35
LCchar	2	8015	1F4F
Linefeed	2	7981	1F2D
Out1	2	8034	1F62
Out2	2	8036	1F64
PAD	2	43008	A800
PADD	2	43010	A802
Return	2	8083	1F93
SFTflag	2	8187	1FFB
Start	2	7904	1EE0
TOUT	2	35488	8AA0
Temp	2	8188	1FFC
Timer	2	42007	A417
Type	2	7916	1EEC
TypeOn	2	8191	1FFF
Xspace	2	7961	1F19

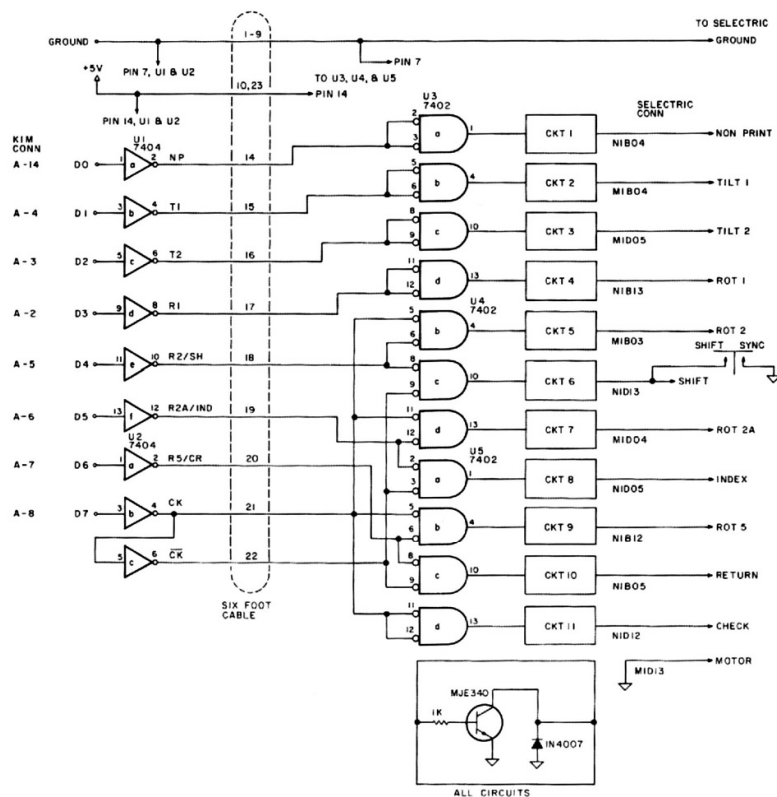


Fig. 1. The complete hardware interface schematic.

Those familiar with the SYM may have already noticed that the program is located from \$1EE4 to \$1FFF, which would only be available if the SYM had a full 8K of RAM. Or you may have noticed that the Synertek logo and name have been covered up with another added board that has DIP plugs con-

nected to the sockets for the SYM's U12 and U19. If so, you are right!

This little board does expand the SYM to a full 8K of RAM. It is double-sided and requires plated through holes. Hidden jumpers run to pins of SYM's U1 to complete the required connections. The original SYM U12

and U19 plus eight more 2114s mount on this expansion board. The full 8K allows fairly extensive BASIC, Tiny BASIC or assembly-language programs to be used before the SYM runs out of memory space.

To expand memory beyond 8K would definitely require buffering such as used on the mem-

ory board in the abovementioned *Microcomputing* article. This little board does not have room for the buffer ICs dictated by good engineering practices. However, many of them are in use on SYMs other than mine without any reported problems.

Since the SYM vectors all of its inputs and outputs through a common memory location in its system RAM, interfacing BASIC or other application programs to the Selectric driver software is easy—just change the vector! Instructions for doing this are contained in the comments of Listing 2.

### Conclusion

It is not difficult to interface an IBM Selectric I/O typewriter to a microcomputer, such as the KIM-1 and SYM-1, that has an eight-bit output port and an on-board timer. Excellent, although somewhat slow, print quality is obtainable with minimal hardware and software required. The KIM or SYM can now be used for those applications such as text editing that require hard copy. (The KIM was used to prepare this article.) It helps to have a hard-copy listing of those programs you're trying to debug, too! ■

### Notes

Blank PC boards and instructions to expand the SYM to 8K of RAM are available from the author for \$5 each plus a self-addressed stamped envelope. KIM-format cassette tapes of the Selectric interface software (specify version) will be provided for \$2.50.